

# machine learning prerequisites workshop

## probability and statistics

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Sharif University  
of Technology

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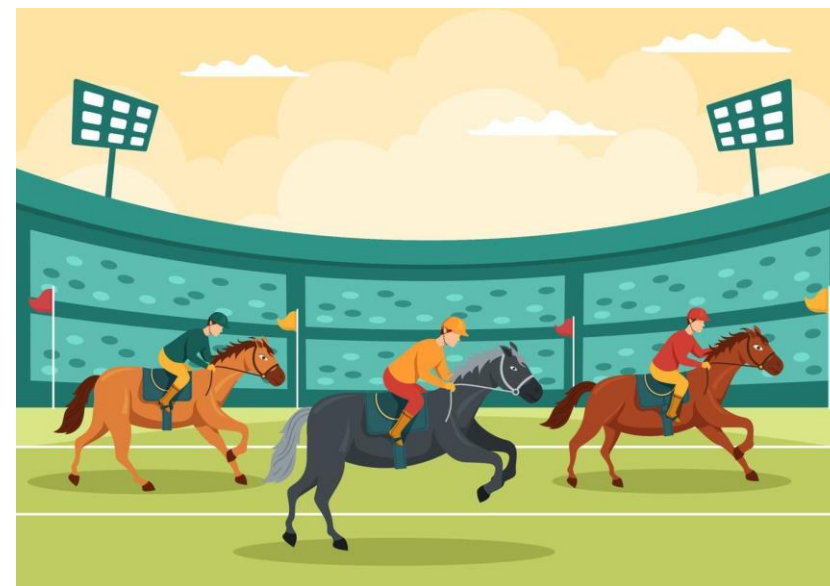
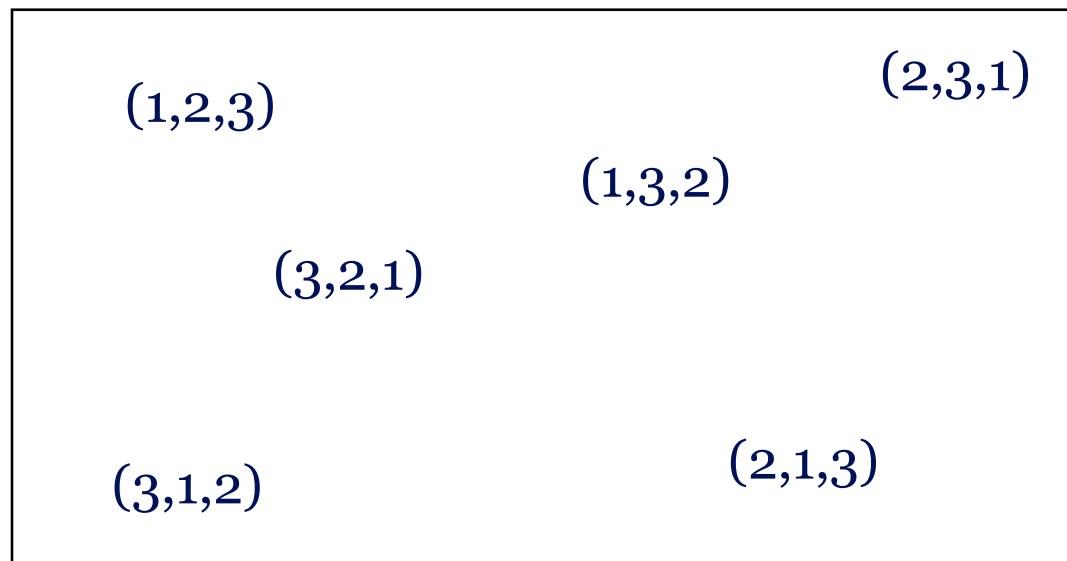
Maximum Likelihood Estimation (MLE)

Maximum A Posteriori (MAP)



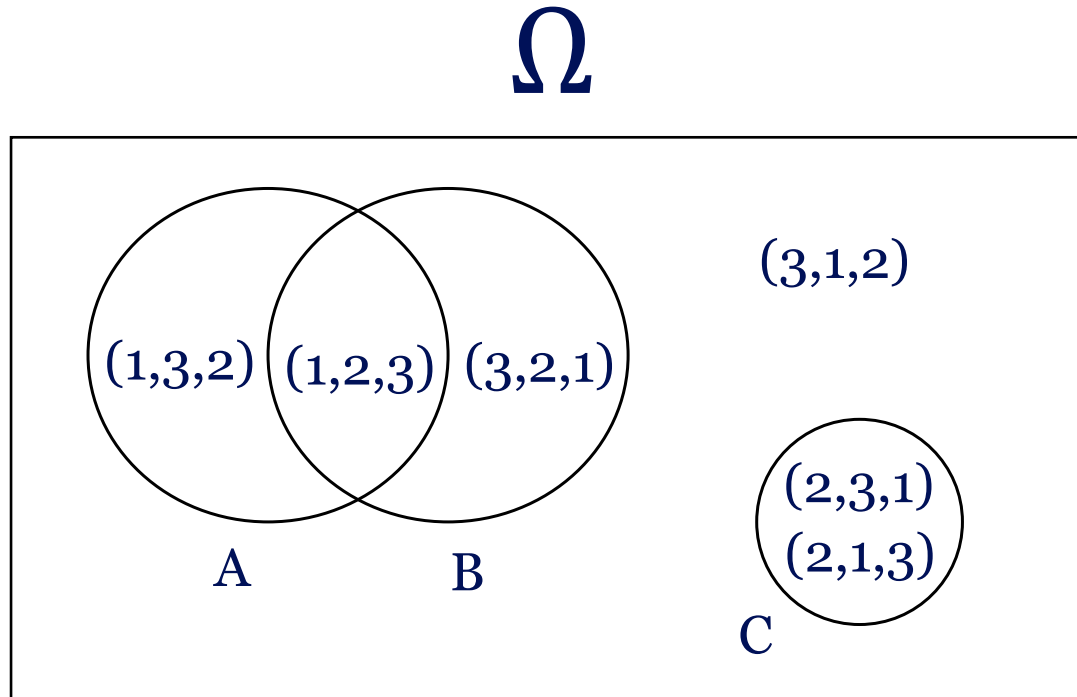
# فضای نمونه (Sample Space)

( شماره شرکت کننده سوم , شماره شرکت کننده دوم , شماره شرکت کننده اول )

$$\Omega$$


$$\Omega = \{(1,2,3), (1,3,2), (2,1,3), (2,3,1), (3,1,2), (3,2,1)\}$$

# پیشامد (Event)



$$A = \{(1,2,3), (1,3,2)\}$$

$$B = \{(1,2,3), (3,2,1)\}$$

$$C = \{(2,3,1), (2,1,3)\}$$

# اصول احتمال (Probability Axioms)

(۱) به ازای هر پیشامد داریم:  $0 \leq P(A) \leq 1$

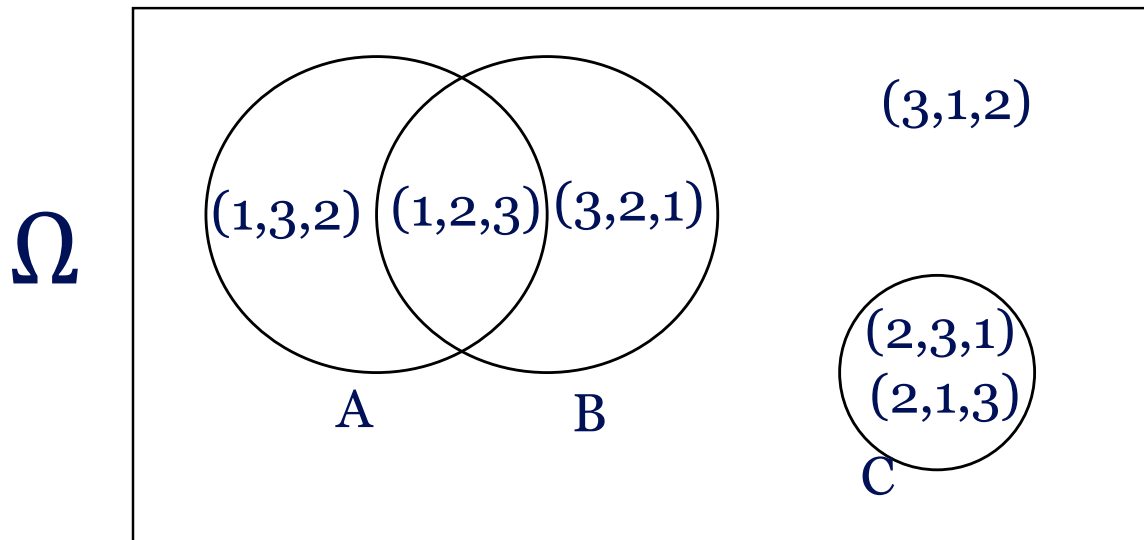
$$P(\Omega) = 1 \quad (۲)$$

(۳) برای پیشامدهای ناسازگار داریم:  $P(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} P(A_i)$



# احتمال شرطی (Conditional Probability)

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$



$$P(A|B) = \frac{\frac{1}{6}}{\frac{1}{3}} = \frac{1}{2}$$

# پیشامدهای مستقل (Independent Events)

$$P(A \cap B) = P(A)P(B)$$



# قضیه بیز (Bayes Theorem)

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$



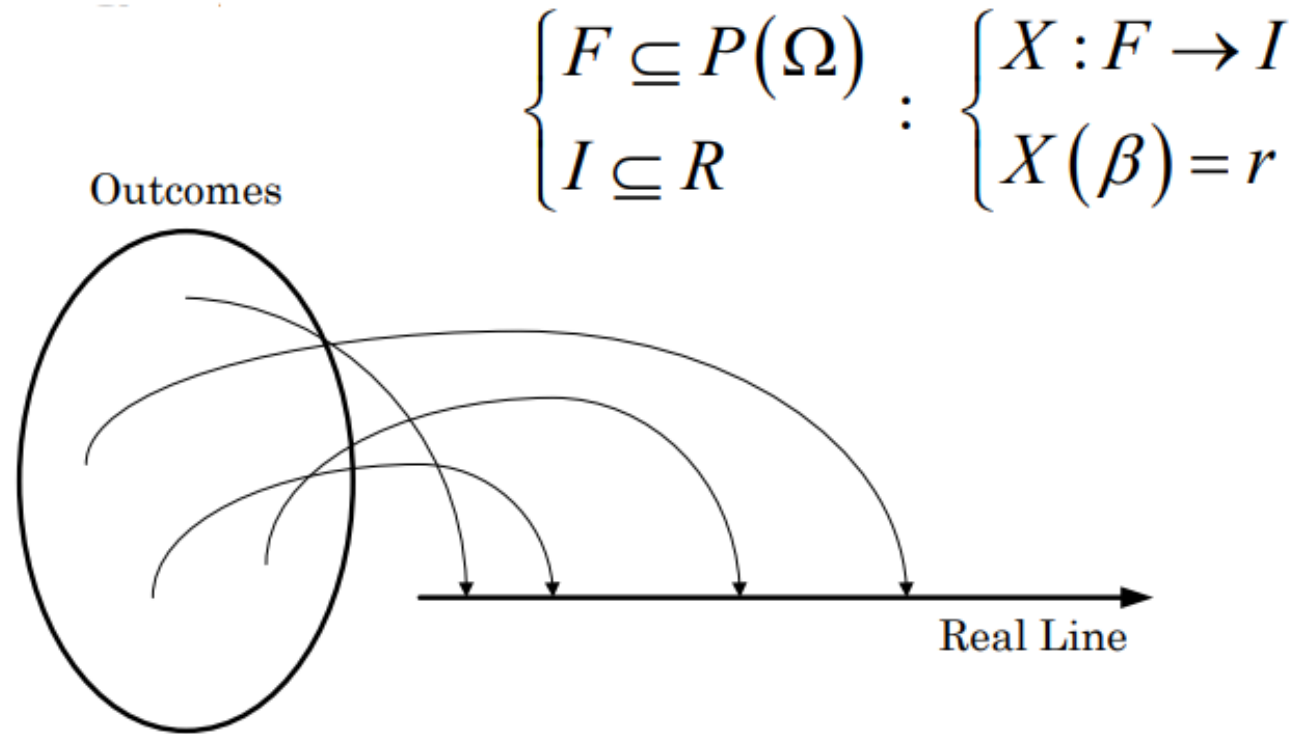


# قانون احتمال کل (Law of total probability)

$$P(A) = \sum_{i=1}^n P(A \cap B_i)$$



# متغیر تصادفی (Random Variable)



(۱) پیوسته : تابع چگالی احتمال

(۲) گسسته : تابع جرم احتمال

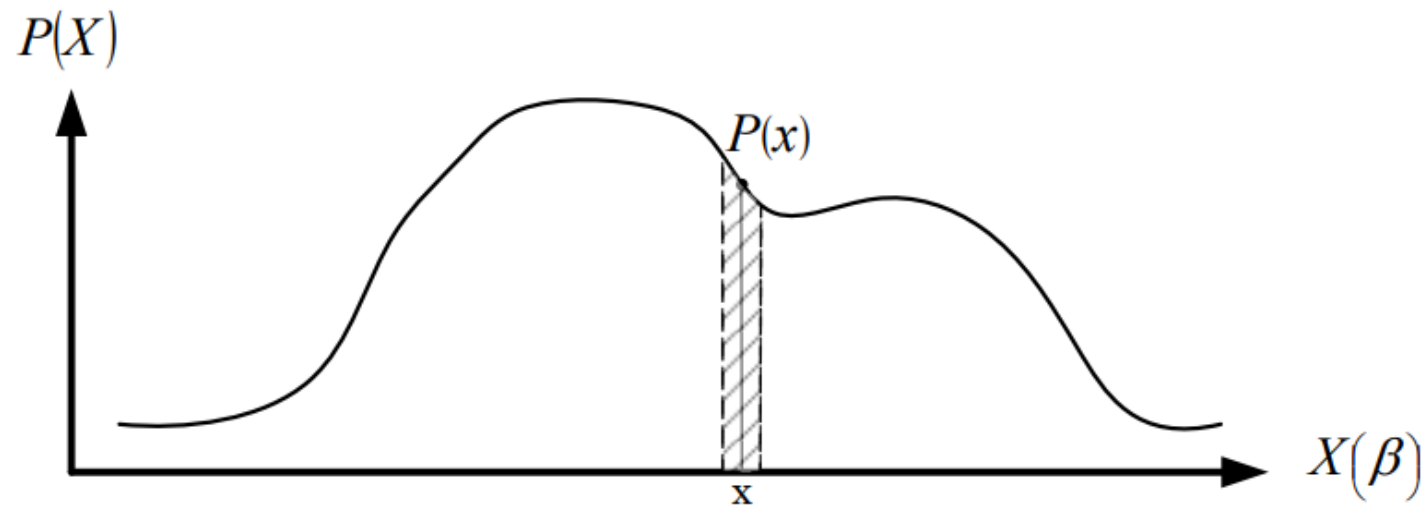
# تابع جرم احتمال (probability mass function - PMF)

$$f_X(x) = P(X = x)$$



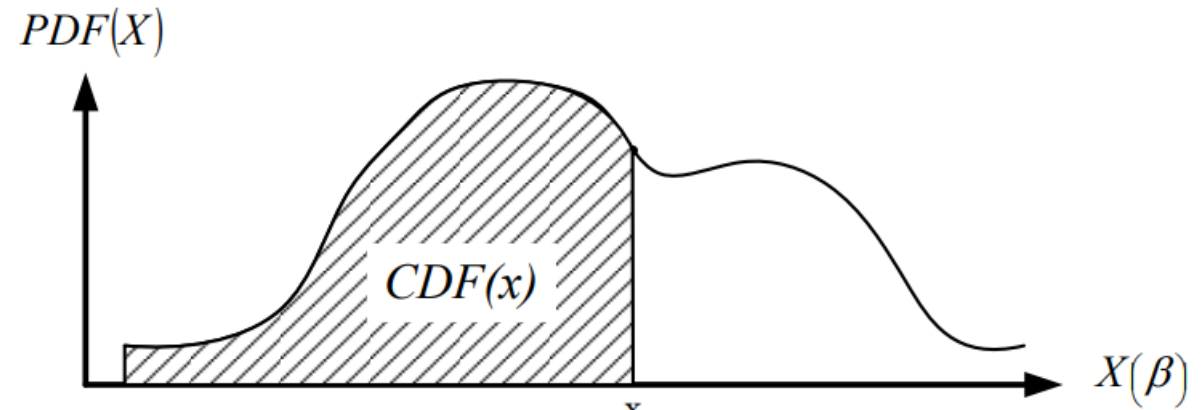
# تابع چگالی احتمال (probability density function - PDF)

$$P(a \leq X \leq b) = \int_a^b f_X(x) dx$$



# تابع توزیع تجمعی (cumulative distribution function - CDF)

$$F_X(x) = P(X \leq x)$$



$$F_X(x) = \begin{cases} F_X(x) = \sum_{X \leq x} f_X(x) \\ F_X(x) = \int_{-\infty}^x f_X(x) \Rightarrow \frac{d}{dx} F_X(x) = f_X(x) \end{cases}$$

# امید ریاضی (Expected Value)

$$E[X] = \mu = \begin{cases} \sum_{x \in \Omega} x f_X(x) \\ \int_{-\infty}^{\infty} x f_X(x) \end{cases}$$

$$E[aX + bY + c] = aE[X] + bE[Y] + c$$

$$\hat{\mu} = \frac{\sum_{i=1}^n x_i}{n}$$



# Law of the unconscious statistician - LOTUS

$$E[g(X)] = \begin{cases} \sum_{x \in \Omega} g(x) f_X(x) \\ \int_{-\infty}^{\infty} g(x) f_X(x) \end{cases}$$



# واریانس (Variance)

$$\text{Var}(X) = \sigma^2 = E[(X - \mu)^2] = E[X^2] - E[X]^2$$

$$\mu = E[X]$$

$$\text{Var}(X) = \begin{cases} \sum_{x \in \Omega} (X - \mu)^2 f_X(x) \\ \int_{-\infty}^{\infty} (x - \mu)^2 f_X(x) \end{cases} \quad \widehat{\sigma^2} = \frac{\sum_{i=1}^n (x_i - \hat{\mu})^2}{n-1}$$

$$\text{Var}(aX + b) = a^2 \text{Var}(X)$$





# کوواریانس (Covariance)

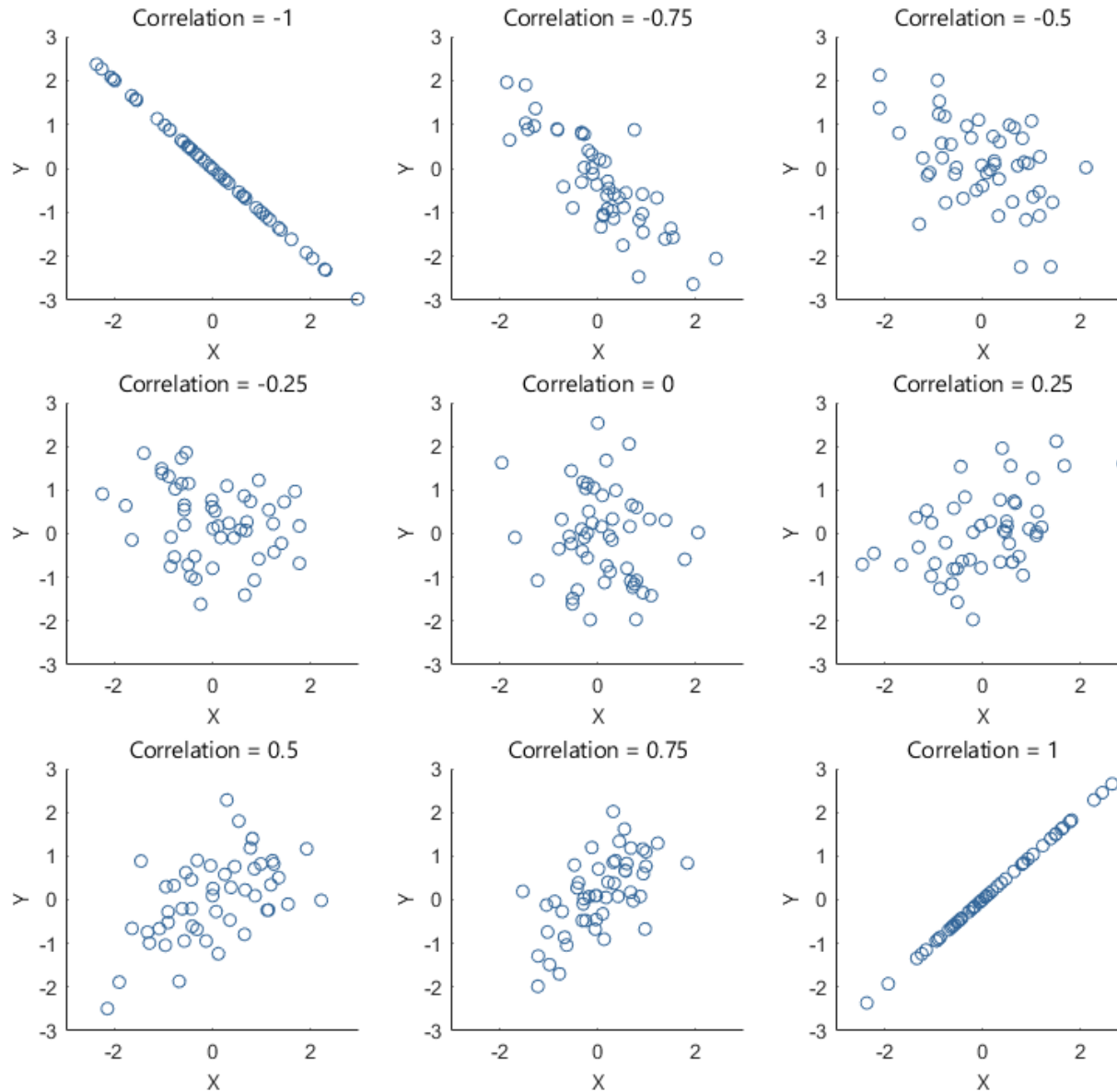
$$\text{Cov}(X, Y) = E[(X - \mu_X)(Y - \mu_Y)]$$

$$\text{Cov}(X, Y) = \frac{\sum((x_i - \bar{x})(y_i - \bar{y}))}{n - 1}$$

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$$



# همبستگی (correlation)

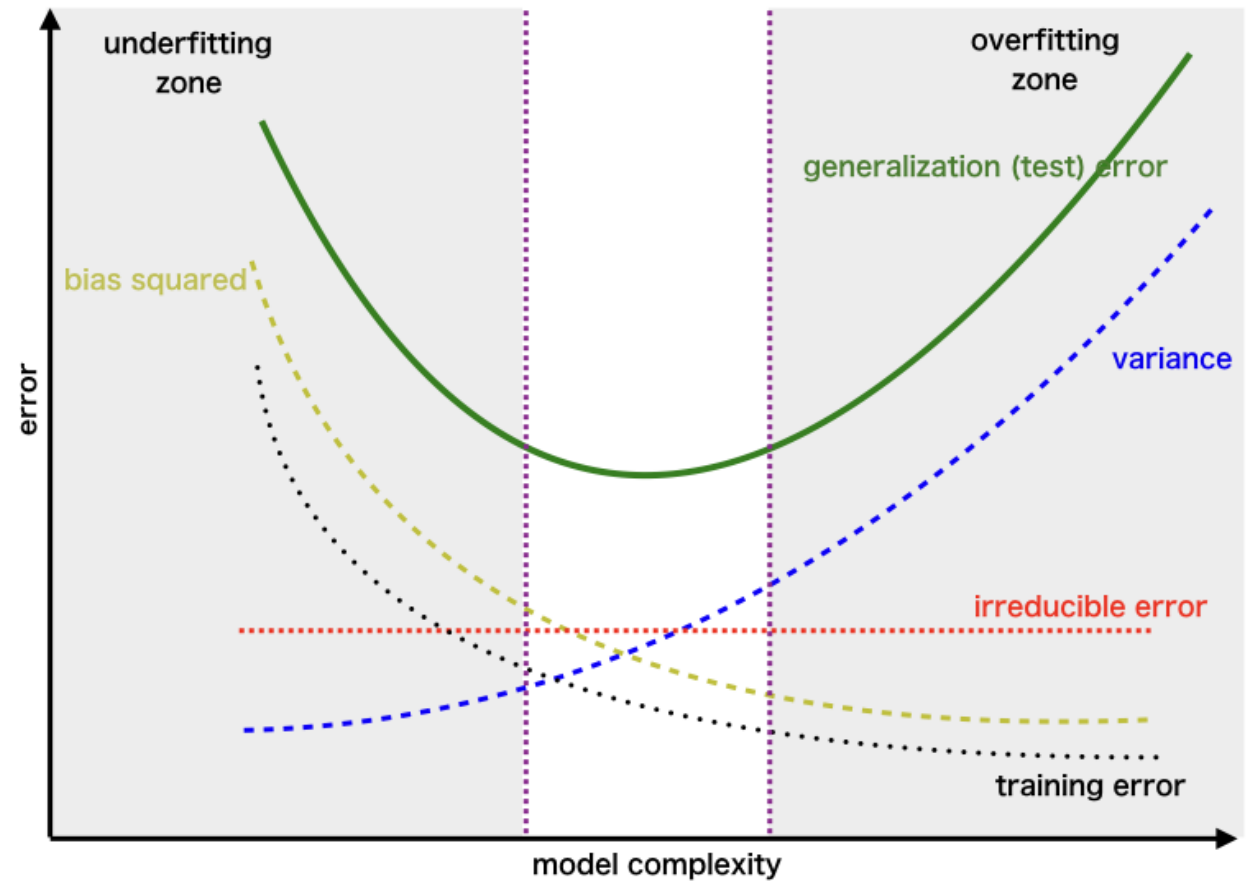
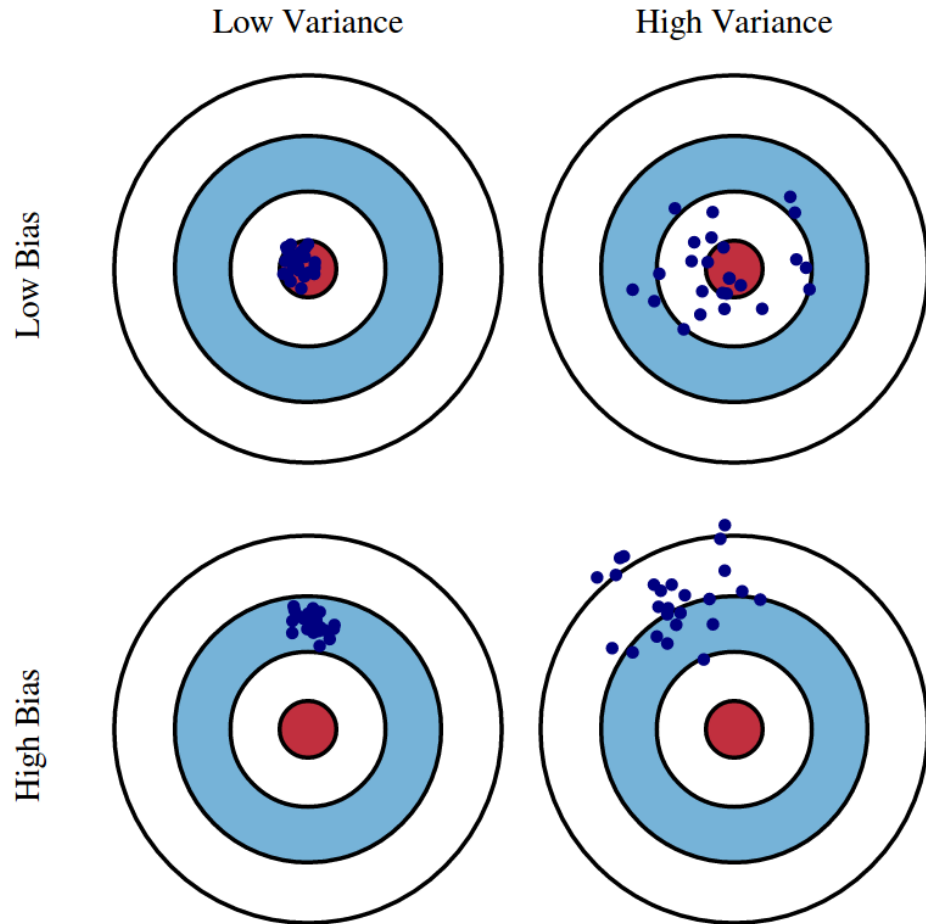


$$\text{Corr}(X, Y) = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X)\text{Var}(Y)}}$$



$$\text{Bias}(\hat{\theta}) = E[\hat{\theta} - \theta]$$

# بایاس-واریانس ترید آف (bias-variance tradeoff)



# متغیر تصادفی برنولی (Bernoulli)

$$X \sim Br(p)$$

$$P(X = x) = \begin{cases} p & x = 1 \\ 1 - p & x = 0 \\ 0 & \text{otherwise} \end{cases}$$

$$f_X(x) = p^x (1 - p)^{1-x}$$

$$E[X] = p$$

$$Var(X) = p(1 - p)$$



# متغیر تصادفی دوجمله‌ای (Binomial)

$$X \sim \text{Bin}(n, p)$$

$$P(X = x) = \begin{cases} \binom{n}{x} p^x (1-p)^{n-x} & 0 \leq x \leq n \\ 0 & \text{otherwise} \end{cases}$$

$$E[X] = np$$

$$\text{Var}(X) = np(1-p)$$



# متغیر تصادفی یکنواخت (Uniform Distribution)

$$X \sim U(a, b)$$

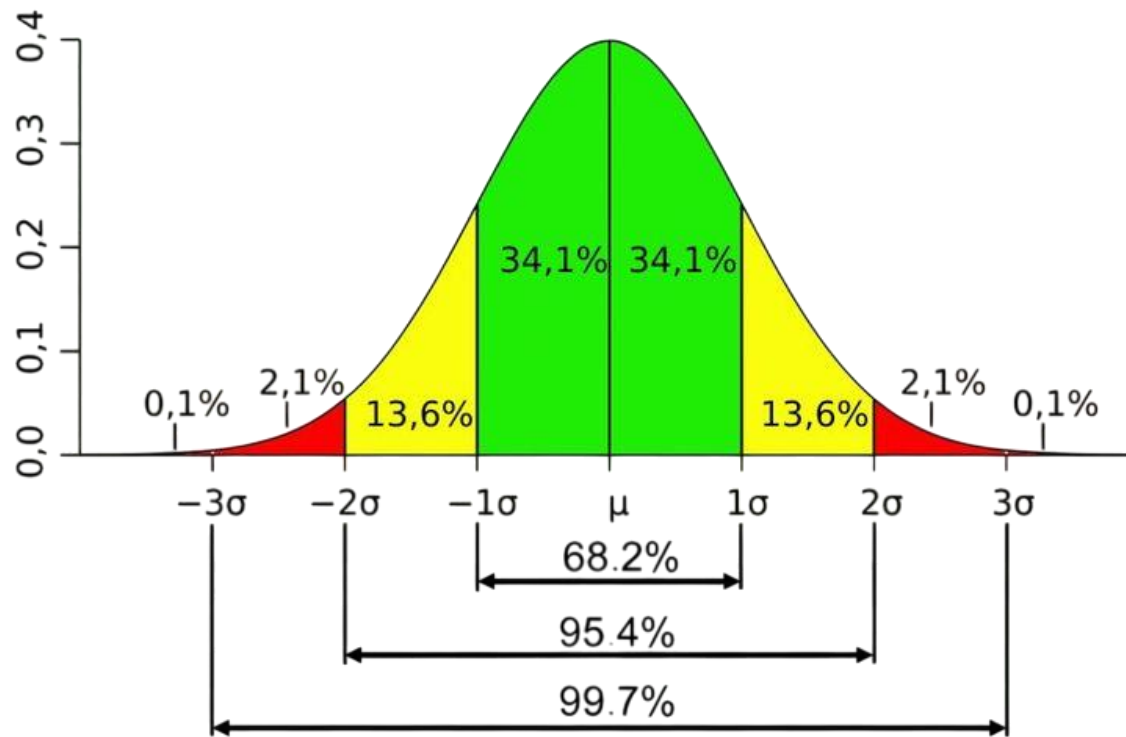
$$f_X(x) = \begin{cases} \frac{1}{b-a} & a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$$

$$E[X] = \frac{a+b}{2}$$

$$\text{Var}(X) = \frac{(b-a)^2}{12}$$



# توزیع نرمال (Normal Distribution)



$$X \sim N(\mu, \sigma^2)$$

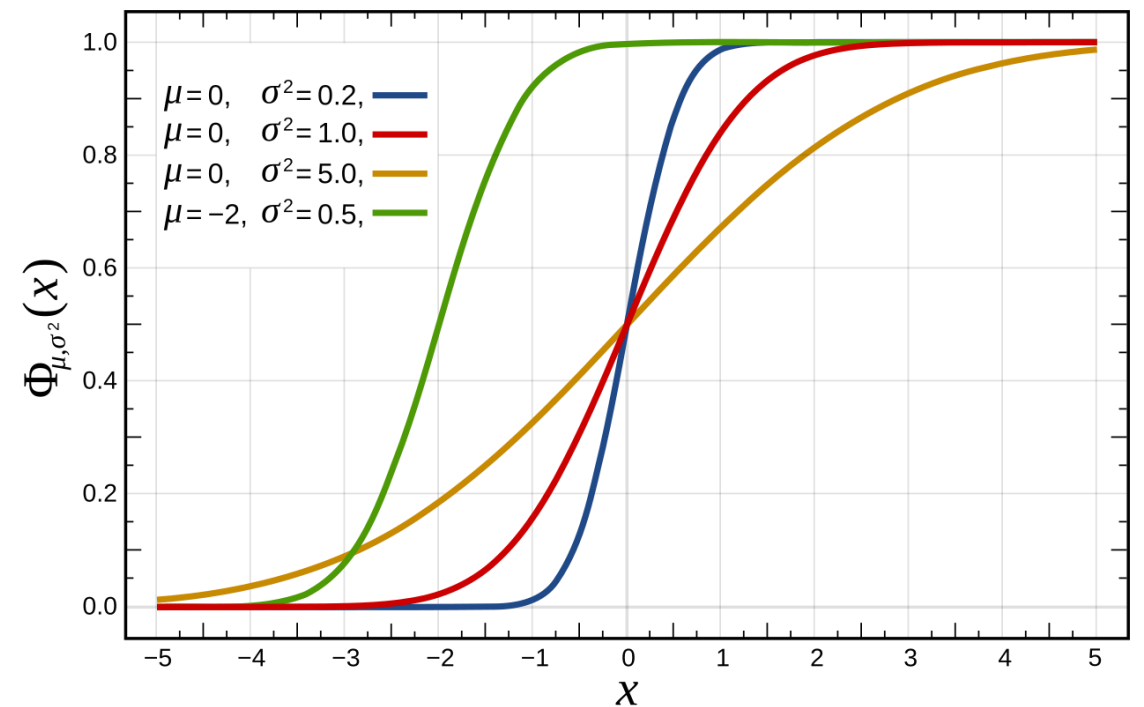
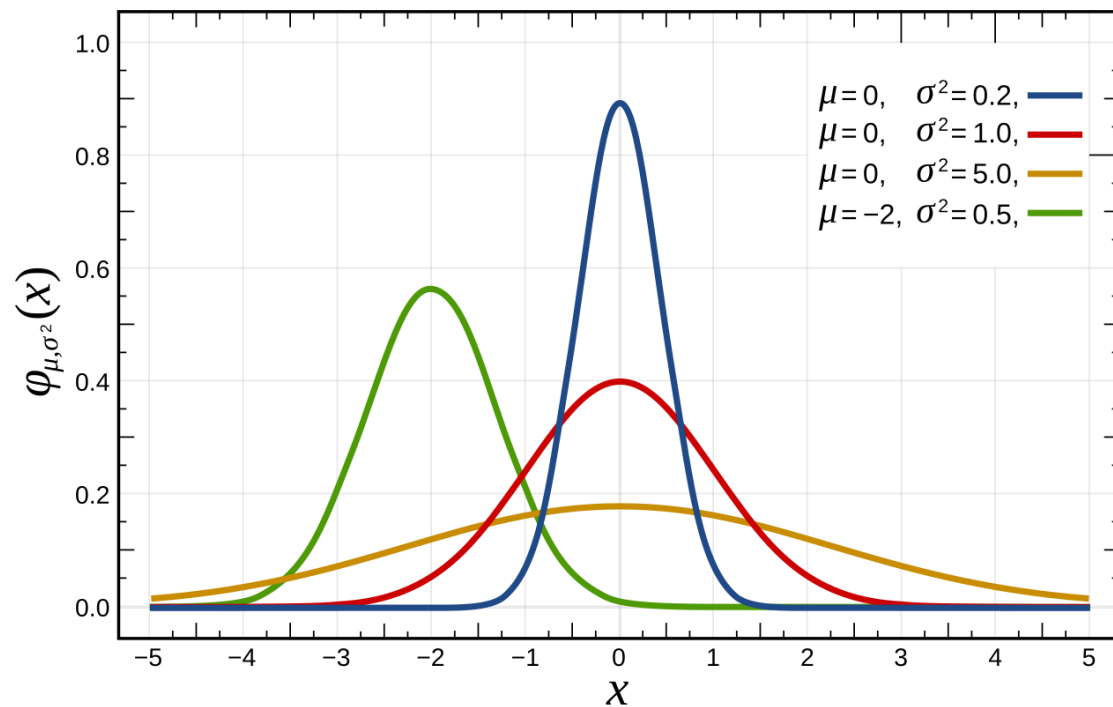
$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

$$E[X] = \mu$$

$$Var(X) = \sigma^2$$



# توزیع نرمال (Normal Distribution)



# توزيع احتمال توام (Joint probability distribution)

$$F_{X,Y}(x, y) = P(X \leq x, Y \leq y) = \int_{-\infty}^x \int_{-\infty}^y f_{X,Y}(x, y) dy dx$$

$$f_{X,Y}(x, y) = \frac{\partial^2}{\partial x \partial y} F_{X,Y}(x, y)$$

# قضیه حد مرکزی (Central Limit Theorem)

اگر  $X_1, X_2, \dots, X_n$  مستقل و دارای توزیع یکسان (idd) باشند به طوری که  $E[X_i] = \mu$  و  $Var[X_i] = \sigma^2$ ، آنگاه:

$$\bar{X} \sim N\left(\mu, \frac{\sigma^2}{n}\right)$$

\* idd : Independent and Identically Distributed



# قانون اعداد بزرگ (law of large numbers)

اگر  $X_1, X_2, \dots, X_n$  مستقل و دارای توزیع یکسان (idd) باشند به طوری که  $E[X_i] = \mu$ ، به ازای هر  $\varepsilon > 0$  داریم:

$$P \left\{ \left| \frac{X_1 + X_2 + \dots + X_n}{n} - \mu \right| < \varepsilon \right\} \rightarrow 0 \quad \text{اگر } n \rightarrow \infty$$

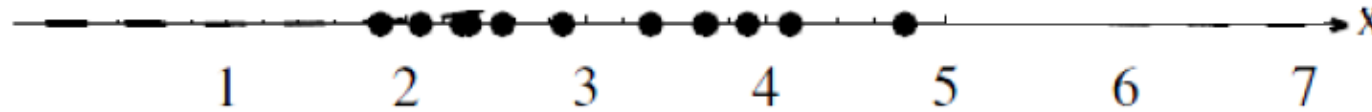
یا به صورت دیگر:

$$\lim_{n \rightarrow \infty} \frac{X_1 + X_2 + \dots + X_n}{n} = \mu$$

\* idd : Independent and Identically Distributed



# Maximum Likelihood Estimation (MLE)



$$P(x|\mu) = N(x|\mu, 1)$$

# Likelihood, Posterior and Prior

$$\boxed{P(\theta|Y)} = \frac{P(Y|\theta) P(\theta)}{P(Y)}$$

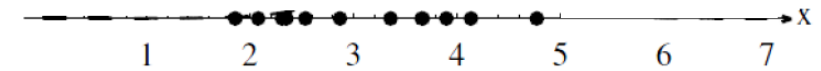
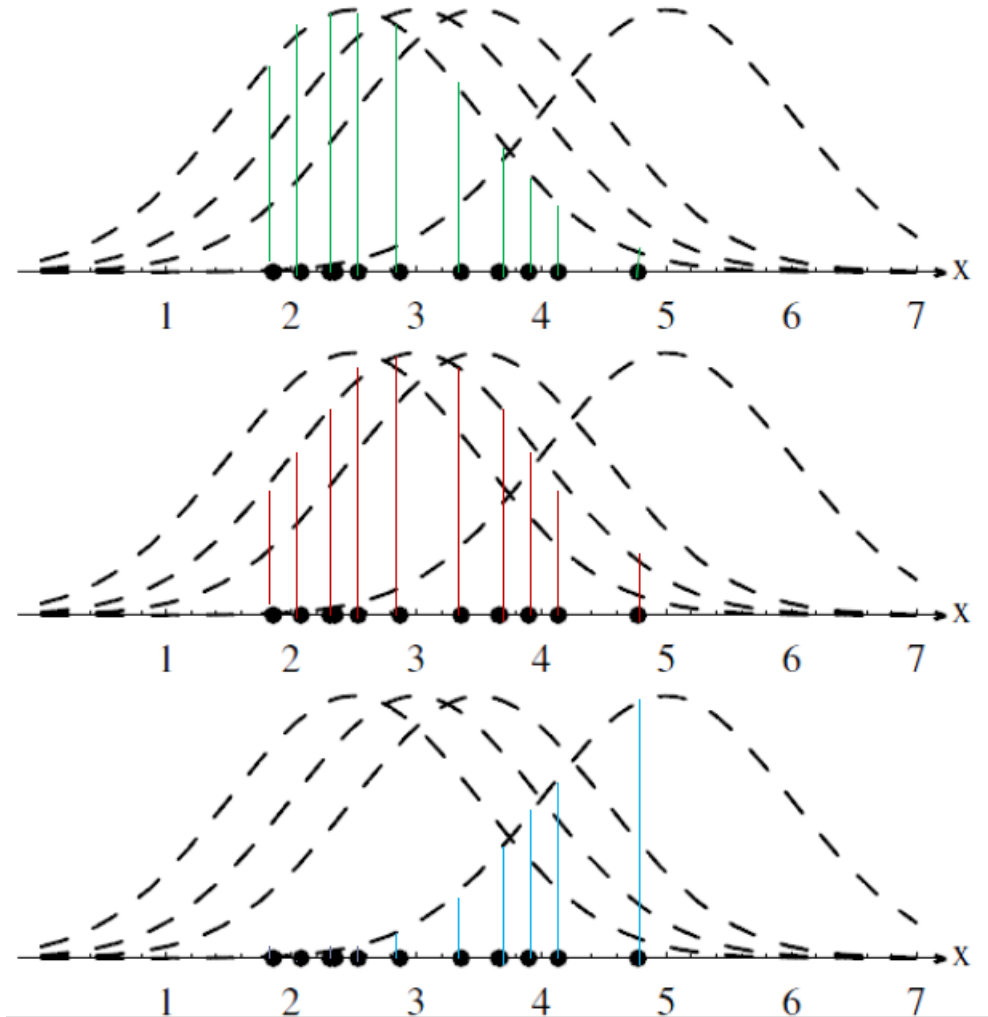
↑  
Posterior

$$\propto \boxed{P(Y|\theta)} \boxed{P(\theta)}$$

↑                      ↑  
Likelihood                      Prior



# Maximum Likelihood Estimation (MLE)



$$P(x|\mu) = N(x|\mu, 1)$$



# Maximum Likelihood Estimation (MLE)

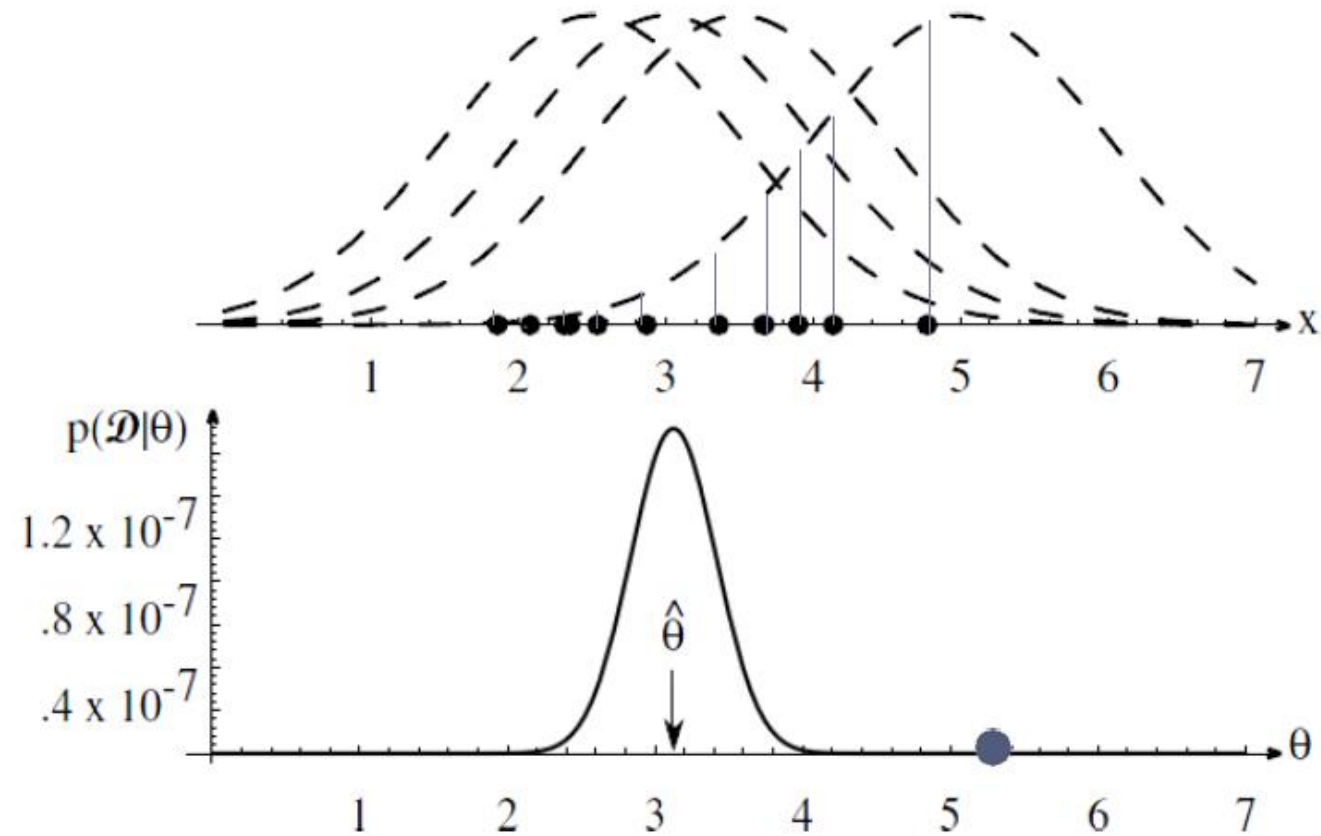
$$P(X|\theta) = \prod_{i=1}^n P(x^{(i)}|\theta)$$

$$\theta_{ML} = \operatorname{argmax} P(X|\theta)$$

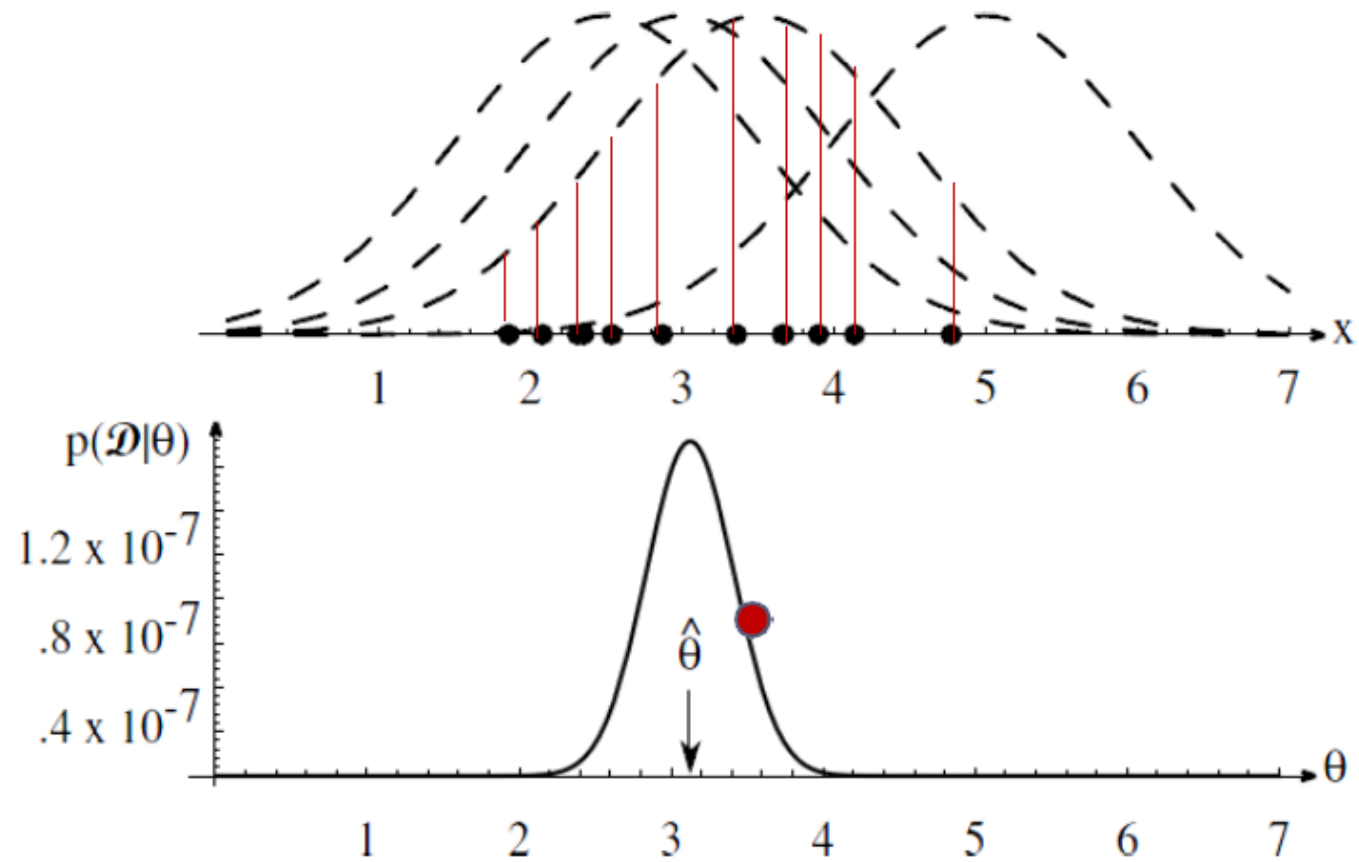




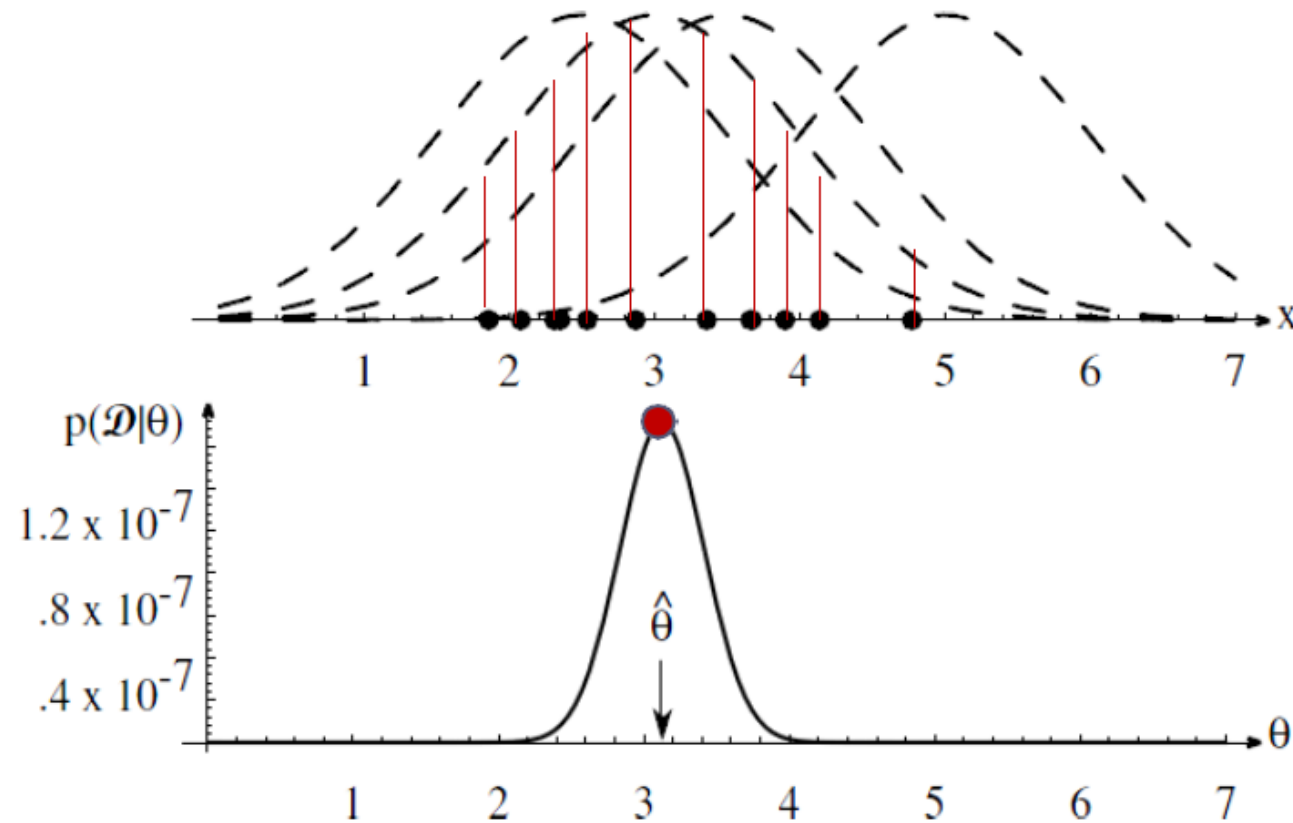
# Maximum Likelihood Estimation (MLE)



# Maximum A Posteriori (MAP)



# Maximum A Posteriori (MAP)



# Maximum Likelihood Estimation (MLE)

$$\mathcal{L}(\boldsymbol{\theta}) = \ln p(\mathcal{D}|\boldsymbol{\theta}) = \ln \prod_{i=1}^N p(\mathbf{x}^{(i)}|\boldsymbol{\theta}) = \sum_{i=1}^N \ln p(\mathbf{x}^{(i)}|\boldsymbol{\theta})$$

$$\hat{\boldsymbol{\theta}}_{ML} = \operatorname{argmax}_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}) = \operatorname{argmax}_{\boldsymbol{\theta}} \sum_{i=1}^N \ln p(\mathbf{x}^{(i)}|\boldsymbol{\theta})$$



# MLE Bernoulli

Given:  $\mathcal{D} = \{x^{(1)}, x^{(2)}, \dots, x^{(N)}\}$ ,  $m$  heads (1),  $N - m$  tails (0)

$$p(x|\theta) = \theta^x (1 - \theta)^{1-x}$$

$$p(\mathcal{D}|\theta) = \prod_{i=1}^N p(x^{(i)}|\theta) = \prod_{i=1}^N \theta^{x^{(i)}} (1 - \theta)^{1-x^{(i)}}$$

$$\ln p(\mathcal{D}|\theta) = \sum_{i=1}^N \ln p(x^{(i)}|\theta) = \sum_{i=1}^N \{x^{(i)} \ln \theta + (1 - x^{(i)}) \ln(1 - \theta)\}$$

$$\frac{\partial \ln p(\mathcal{D}|\theta)}{\partial \theta} = 0 \Rightarrow \theta_{ML} = \frac{\sum_{i=1}^N x^{(i)}}{N} = \frac{m}{N}$$



# Maximum A Posteriori (MAP)

MAP estimation

$$\hat{\boldsymbol{\theta}}_{MAP} = \operatorname{argmax}_{\boldsymbol{\theta}} p(\boldsymbol{\theta}|\mathcal{D})$$

Since  $p(\boldsymbol{\theta}|\mathcal{D}) \propto p(\mathcal{D}|\boldsymbol{\theta})p(\boldsymbol{\theta})$

$$\hat{\boldsymbol{\theta}}_{MAP} = \operatorname{argmax}_{\boldsymbol{\theta}} p(\mathcal{D}|\boldsymbol{\theta})p(\boldsymbol{\theta})$$



# Gaussian MAP

$$\begin{aligned} p(x|\mu) &\sim N(\mu, \sigma^2) && \mu \text{ is the only unknown parameter} \\ p(\mu|\mu_0) &\sim N(\mu_0, \sigma_0^2) && \mu_0 \text{ and } \sigma_0 \text{ are known} \end{aligned}$$

$$\begin{aligned} \frac{d}{d\mu} \ln \left( p(\mu) \prod_{i=1}^N p(x^{(i)}|\mu) \right) &= 0 \\ \Rightarrow \sum_{i=1}^N \frac{1}{\sigma^2} (x^{(i)} - \mu) - \frac{1}{\sigma_0^2} (\mu - \mu_0) &= 0 \\ \Rightarrow \hat{\mu}_{MAP} &= \frac{\mu_0 + \frac{\sigma_0^2}{\sigma^2} \sum_{i=1}^N x^{(i)}}{1 + \frac{\sigma_0^2}{\sigma^2} N} \end{aligned}$$



- Stochastic Processes - Hamid R. Rabiee
- machine learning – Ali Sharifi-Zarchi
- machine learning - Mahdieh Soleymani Baghshah